## **REMARKS**

The objections of numbered paragraphs 1 and 3 of the Office Action mailed September 29, 2004, are surprising to the Applicants, since a guide member guided in rotation is illustrated on Fig. 10, which is self-explanatory.

Applicants believe newly proposed claims 18-24 will satisfactorily address the objections specified in paragraphs 4 and 5 of the Office Action mailed September 29, 2004.

Regarding paragraphs 6 and 7 of the Office Action mailed September 29, 2004, namely the objections based on Roy et al., U.S. Patent No. 6,497,548, the Examiner is please asked to note that the device described in that document, in particular in relation to Fig. 9 of Roy et al., comprises a terminal element 60 secured to an element 415 that can be considered to be a platform. Element 60 can be positioned and oriented in space according to four degrees of freedom by means of three legs supported by carriages. However, this device does not comprise any auxiliary structure arranged to transmit to the terminal element a pivot movement about an axis belonging to the platform, such as claimed in new claim 18 of the Applicants. As a matter of fact, the device of Roy et al. is totally symmetrical. To obtain a pivotation of the terminal element about an axis belonging to the platform, it would be necessary to move the three carriages according to a well-determined program, while with the device of the present invention rotation of the terminal element about an axis belonging to the platform can be obtain by means of moving only the auxiliary guiding member. The device of the present invention is therefore much simpler and allows enhanced precision due to the property of angular stiffness strength tracking.

Serial No. 10/648,730

Amendment After Office Action Mailed September 29, 2004

Page 6 of 7

For all these foregoing reasons, Applicants respectfully requests entry of the foregoing claims, reconsideration of the present application in light thereof, and in light of the foregoing remarks, and then allowance of new claims 18-24 over all the prior art of record.

Respectfully submitted,

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Serial No. 10/648,730

Amendment After Office Action Mailed September 29, 2004

Page 7 of 7